

## Key to Test 2

(1)

1 a) Denote by

$$f(t, x, y) = \ln(x+y+1) + 4$$

and

$$g(t, x, y) = \sin(x+y-1) + 2.$$

All the functions  $f, g, f_x, f_y, g_x,$  and  $g_y$  are continuous

in  $t, x,$  and  $y$  in an open neighborhood of

$x(0) = 1$  and  $y(0) = -1$ . For this reason, the fundamental existence and uniqueness result (see Theorem 4.1 page 133) applies.

b) Since  $f(t, 0, -1) = \ln(0) + 4$  is undefined, our fundamental existence and uniqueness result (again Theorem 4.1) does not apply.

c) Denote by

$$f(t, x, y) = 3x + 5y + ax^2$$

and

$$g(t, x, y) = 2x - y + e^t$$

For all values of  $a$ ,  $f, g, f_x, f_y, g_x,$  and  $g_y$  are continuous for all values of  $t, x,$  and  $y$ . In this case, Theorem 4.1 applies to all initial conditions for any choice of  $a$ .

d) Theorem 4.1 only guarantees local existence of solutions. Theorem 5.1 (see page 160) guarantees existence of unique solutions on the whole interval (in this case for all  $t$ ), but this Theorem 5.1 only applies to linear systems. In this case, we only have existence and uniqueness of solutions that are defined for all  $t$  in the special case that  $a=0$ . (When  $a \neq 0$ , this system is not linear.)

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2 a) Note that

$$A \tilde{x}_1(t) = \begin{pmatrix} -2 & 3 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} e^{4t} \\ 2e^{4t} \end{pmatrix} = \begin{pmatrix} 4e^{4t} \\ 8e^{4t} \end{pmatrix} = \tilde{x}_1'(t)$$

and similarly

$$A \tilde{x}_2(t) = \begin{pmatrix} -2 & 3 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} -3e^{-3t} \\ e^{-3t} \end{pmatrix} = \begin{pmatrix} 9e^{-3t} \\ -3e^{-3t} \end{pmatrix} = \tilde{x}_2'(t)$$

and thus both  $\tilde{x}_1$  and  $\tilde{x}_2$  are solutions of the linear homogeneous system:

$$\tilde{x}' = A\tilde{x}.$$

The solution matrix

$$\Phi(t) = (\tilde{x}_1(t) \quad \tilde{x}_2(t)) = \begin{pmatrix} e^{4t} & -3e^{-3t} \\ 2e^{4t} & e^{-3t} \end{pmatrix} \text{ is fundamental}$$

because  $\det(\Phi(0)) = \det \begin{pmatrix} 1 & -3 \\ 2 & 1 \end{pmatrix} = 7 \neq 0$ .

b) In general, the solution of a linear homogeneous system's I.V.P. at  $t=0$  is given by

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$$\vec{x}(t) = \Phi(t) \Phi(0)^{-1} \vec{x}(0)$$

$$= \begin{pmatrix} e^{4t} & -3e^{-3t} \\ 2e^{4t} & e^{-3t} \end{pmatrix} \cdot \frac{1}{7} \begin{pmatrix} 1 & 3 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$= \frac{1}{7} \begin{pmatrix} e^{4t} & -3e^{-3t} \\ 2e^{4t} & e^{-3t} \end{pmatrix} \begin{pmatrix} -2 \\ -3 \end{pmatrix}$$

$$= \frac{1}{7} \begin{pmatrix} -2e^{4t} + 9e^{-3t} \\ -4e^{4t} - 3e^{-3t} \end{pmatrix}.$$

3) Let  $A = \begin{pmatrix} -3 & 5 \\ -2 & 3 \end{pmatrix}$  and  $\Phi(t) = \begin{pmatrix} 5\cos(t) & 5\sin(t) \\ 3\cos(t) - \sin(t) & \cos(t) + 3\sin(t) \end{pmatrix}$

check that:

$$A\Phi(t) = \begin{pmatrix} -3 & 5 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} 5\cos(t) & 5\sin(t) \\ 3\cos(t) - \sin(t) & \cos(t) + 3\sin(t) \end{pmatrix}$$

$$= \begin{pmatrix} -15\cos(t) + 5(3\cos(t) - \sin(t)) & -15\sin(t) + 5(\cos(t) + 3\sin(t)) \\ -10\cos(t) + 3(3\cos(t) - \sin(t)) & -10\sin(t) + 3(\cos(t) + 3\sin(t)) \end{pmatrix}$$

$$= \begin{pmatrix} -5\sin(t) & +5\cos(t) \\ -\cos(t) - 3\sin(t) & 3\cos(t) - \sin(t) \end{pmatrix}$$

$$= \Phi'(t) \quad \text{i.e. } \Phi(t) \text{ is a solution matrix.}$$

To see that  $\Phi(t)$  is fundamental, note that

$$\det(\Phi(0)) = \det \begin{pmatrix} 5 & 0 \\ 3 & 1 \end{pmatrix} = 5 \neq 0.$$

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b) By Variation of constants, the general solution of this non-homogeneous linear system is:

$$x(t) = \Phi(t) \tilde{c} + \Phi(t) \int_0^t \Phi(s)^{-1} \tilde{q}(s) ds$$

where  $\tilde{q}(s) = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ .

Note that

$$\begin{aligned} \det(\Phi(s)) &= \det \begin{pmatrix} 5 \cos(s) & 5 \sin(s) \\ 3 \cos(s) - \sin(s) & \cos(s) + 3 \sin(s) \end{pmatrix} \\ &= 5 \cos(s) (\cos(s) + 3 \sin(s)) - 5 \sin(s) (3 \cos(s) - \sin(s)) \\ &= 5 \cos^2(s) + 15 \sin(s) \cos(s) - 15 \sin(s) \cos(s) + 5 \sin^2(s) \\ &= 5 (\sin^2(s) + \cos^2(s)) = 5 \end{aligned}$$

Thus

$$\Phi(s)^{-1} = \frac{1}{5} \begin{pmatrix} \cos(s) + 3 \sin(s) & -5 \sin(s) \\ \sin(s) - 3 \cos(s) & 5 \cos(s) \end{pmatrix}$$

In this case,

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$$\begin{aligned} \int_0^t \Phi(s)^{-1} \tilde{q}(s) ds &= \int_0^t \frac{1}{5} \begin{pmatrix} \cos(s) + 3\sin(s) & -5\sin(s) \\ \sin(s) - 3\cos(s) & 5\cos(s) \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} ds \\ &= \int_0^t \frac{1}{5} \begin{pmatrix} -\cos(s) - 8\sin(s) \\ -\sin(s) + 8\cos(s) \end{pmatrix} ds \\ &= \frac{1}{5} \begin{pmatrix} -\sin(t) + 8\cos(t) \\ \cos(t) + 8\sin(t) \end{pmatrix} \end{aligned}$$

and so

$$\begin{aligned} \tilde{x}(t) &= \Phi(t) \tilde{c} + \Phi(t) \int_0^t \Phi(s)^{-1} \tilde{q}(s) ds \\ &= \begin{pmatrix} 5\cos(t) & 5\sin(t) \\ 3\cos(t) - \sin(t) & \cos(t) + 3\sin(t) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \\ &\quad + \begin{pmatrix} 5\cos(t) & 5\sin(t) \\ 3\cos(t) - \sin(t) & \cos(t) + 3\sin(t) \end{pmatrix} \frac{1}{5} \begin{pmatrix} -\sin(t) + 8\cos(t) \\ \cos(t) + 8\sin(t) \end{pmatrix} \\ &= \begin{pmatrix} 5c_1 \sin(t) + 5c_2 \cos(t) \\ (3c_2 - c_1) \sin(t) + (c_2 + 3c_1) \cos(t) \end{pmatrix} + \begin{pmatrix} 8 \\ 5 \end{pmatrix} \end{aligned}$$

4) The coefficient matrix  $A = \begin{pmatrix} 2 & 1 \\ -2 & 0 \end{pmatrix}$  has eigenvalues:

a)  $\det(A - \lambda I) = 0 \Leftrightarrow \lambda^2 - 2\lambda + 2 = 0 \Leftrightarrow \lambda_{\pm} = 1 \pm i$

By Putzer: Take  $\lambda_1 = 1+i$  and  $\lambda_2 = 1-i$ .

$$r_1(t) = e^{(1+i)t}$$

$$r_2(t) = e^{(1-i)t} \int_0^t e^{-(1-i)s} \cdot e^{(1+i)s} ds$$

$$\begin{aligned} &= e^t \cdot e^{-it} \int_0^t e^{2is} ds = e^t \cdot e^{-it} \cdot \frac{1}{2i} (e^{2it} - 1) \\ &= e^t \cdot \frac{1}{2i} (e^{it} - e^{-it}) \\ &= e^t \sin(t) \end{aligned}$$

In this case,

$$\Phi(t) = r_1(t)P_1 + r_2(t)P_2$$

$$= e^{(1+i)t} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + e^t \sin(t) \left( \begin{pmatrix} 2 & 1 \\ -2 & 0 \end{pmatrix} - (1+i) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right)$$

$$= e^t \left( \begin{pmatrix} \cos(t) + i \sin(t) & 0 \\ 0 & \cos(t) + i \sin(t) \end{pmatrix} + \sin(t) \begin{pmatrix} 1-i & 1 \\ -2 & -1-i \end{pmatrix} \right)$$

$$= e^t \begin{pmatrix} \cos(t) + \sin(t) & \sin(t) \\ -2 \sin(t) & \cos(t) - \sin(t) \end{pmatrix}$$

b) The solution of the initial value problem is

$$X(t) = \Phi(t) \Phi(0)^{-1} X(0)$$

$$= e^t \begin{pmatrix} \cos(t) + \sin(t) & \sin(t) \\ -2 \sin(t) & \cos(t) - \sin(t) \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$= \begin{pmatrix} e^t \cos(t) \\ -e^t (\sin(t) + \cos(t)) \end{pmatrix}$$

$$5) a) \quad \begin{cases} x' = y \\ y' = 6x + y \end{cases} \Leftrightarrow \tilde{x}' = A\tilde{x} \text{ with } A = \begin{pmatrix} 0 & 1 \\ 6 & 1 \end{pmatrix}$$

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$$b) \quad \det(A - \lambda I) = 0 \Leftrightarrow \lambda^2 - \lambda - 6 = 0$$

$$\Leftrightarrow \lambda_{\pm} = 3, -2$$

$$\lambda = 3 \quad (A - \lambda_1 I) \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 \Leftrightarrow \begin{pmatrix} -3 & 1 \\ 6 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

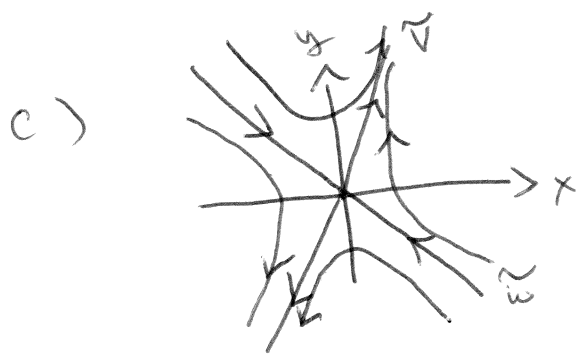
$$\tilde{v} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$\begin{cases} -3v_1 + v_2 = 0 \\ 6v_1 - 2v_2 = 0 \end{cases}$$

$$\lambda_2 = -2 \quad (A - \lambda_2 I) \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = 0 \Leftrightarrow \begin{pmatrix} 2 & 1 \\ 6 & 3 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = 0$$

$$\tilde{w} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$\begin{cases} 2w_1 + w_2 = 0 \\ 6w_1 + 3w_2 = 0 \end{cases}$$



d) The origin is unstable.

