

# Bubble break-up as a two dimensional hydrodynamics problem

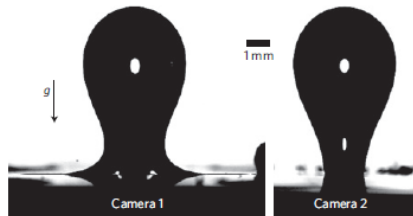
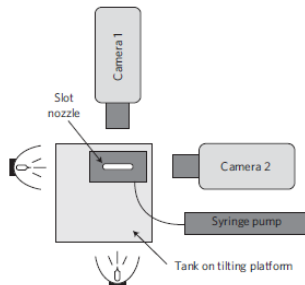
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March 27, 2010

K.Turitsyn, L.Lai, W.Zhang, Phys.Rev.Lett. 123, 124501(2009)

# Experiment



L. Schmidt, N. Keim, W. Zhang, S. Nagel, Nature Physics 2009

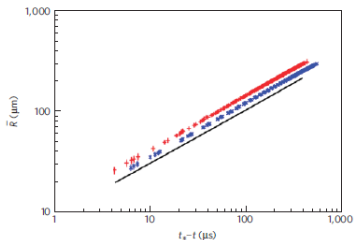
Air bubble is blown from the bottom of water tank. The bubble disconnection process is observed with high-speed video cameras.

# Motivation

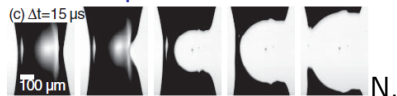
## Disconnection

- ▶ Natural process: formation and breaking of bubbles
- ▶ Singularity formation: Fluid velocity grows like  $V \propto (t_c - t)^{-1/2}$
- ▶ Non-universal behavior: axial symmetry is inevitably broken

## Neck radius



## Final Shape



Keim et.al. Phys. Rev. Lett.  
2006

# Theoretical considerations

- ▶ In axisymmetric situation the neck radius goes like  $R \propto (t_c - t)^\alpha$ , where  
 $\alpha \approx 0.56 \pm 0.01$  (experiment: Keim et.al. PRL 2006) or  
 $\alpha = 1/2 + 1/4\sqrt{t_c - t}$  (theory: Eggers et.al. PRL 2007)
- ▶ Neck becomes more and more slender: slope  
 $R/z \propto (t_c - t)^{\alpha-1/2} \rightarrow 0$
- ▶ Reynolds number:  $\text{Re} \propto (t_c - t)^{2\alpha-1}$ , initially  $\text{Re} \approx 200$
- ▶ Weber number ( $\text{We} = \rho V^2 R / \sigma$ ):  $\text{We} \propto (t_c - t)^{3\alpha-2} \rightarrow \infty$

# Theory: Hydrodynamic equation

In the slider neck approximation the dynamics of neck cross-section as a two-dimensional cavity surrounded by ideal fluid:  $\vec{v} = \nabla\Phi$  with  $\Phi \rightarrow -Q \log r$  when  $r \rightarrow \infty$  and

$$\nabla^2\Phi = 0$$

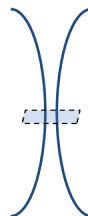
Surface dynamics is governed by two boundary conditions. Kinematic:

$$\frac{d\vec{x}}{dt} = (\partial_t + \nabla\Phi \cdot \nabla)\vec{x} = \nabla\Phi|_S$$

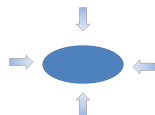
Dynamic:

$$\frac{\partial\Phi}{\partial t} + \frac{1}{2}(\nabla\Phi)^2 \Big|_S = 0$$

Crosssection



2D bubble

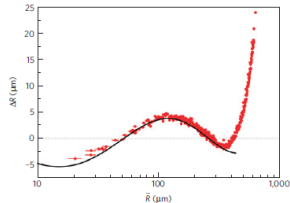
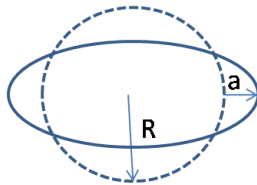


# Linear Stability

There exists a perfect axisymmetric solution:  $R(t) = C(t_c - t)^{1/2}$ . This solution is unstable. If the initial surface is deformed by  $a = \sum a_m(0) \cos(m\varphi)$ , then within linear approximation

$$a_m(t) = a_m(0) \cos\left(\sqrt{m-1} \log \frac{R(0)}{R(t)}\right) \\ \propto \operatorname{Re}(t_c - t)^{i\sqrt{m-1}/2}$$

Relative distortion grows in logarithmic time:  $a_m/R \propto (t_c - t)^{-1/2}$  **Full memory about initial perturbation is preserved!**



Schmidt et.al., Nature Phys.  
2009

# Conformal Mapping

Two-dimensional free surface problem can be effectively solved by mapping the physical surface to a circle in mathematical plane (Dyachenko et.al. 1996).

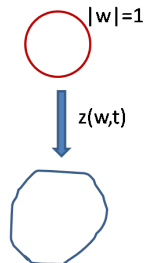
$$z \equiv x + iy = z(w, t), \quad \Phi = \operatorname{Re} \Psi(w, t)$$

$$w \rightarrow \infty : \quad z \rightarrow R w, \quad \Psi \rightarrow -QR \log w$$

where  $z(w, t)$  and  $\Psi(w, t)$  are analytic in the disk  $1 < |w| < \infty$ . It is more convenient to use "Dyachenko" variables:

$$\mathcal{R}(w, t) = \frac{1}{w \partial_w z(w, t)}, \quad \mathcal{V}(w, t) = \frac{\partial_w \Psi(w, t)}{\partial_w z(w, t)}$$

Mapping



# Dyachenko Equations

The dynamical equations can be written as

$$\partial_t \mathcal{R} = w(\partial_w \mathcal{R}) \mathcal{A} \{ \text{Re}[\mathcal{R} \mathcal{V}^*] \} - w \mathcal{R} \partial_w \mathcal{A} \{ \text{Re}[\mathcal{R} \mathcal{V}^*] \}$$

$$\partial_t \mathcal{V} = w(\partial_w \mathcal{V}) \mathcal{A} \{ \text{Re}[\mathcal{R} \mathcal{V}^*] \} - w \mathcal{R} \partial_w \mathcal{A} \{ |\mathcal{V}|^2 \} / 2$$

where  $\mathcal{A}$  is analytic continuation operator:

$$\mathcal{A} \{ F \} (w) = \oint_{|w'|=1} \frac{dw'}{2\pi i w'} \frac{w + w'}{w - w'} F(w')$$

General form of the solution:

$$\mathcal{R}(w, t) = \sum_{n=0}^{\infty} \frac{r_n(t)}{w^{1+n}}, \quad \mathcal{V}(w, t) = \sum_{n=0}^{\infty} \frac{v_n(t)}{w^{1+n}}$$

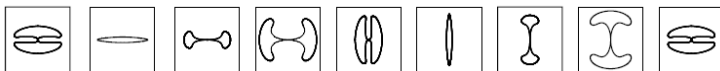
Convenient for numerics: low-order nonlinearity; FFT to perform non-local operation  $\mathcal{A}$ .

# Numerical results

## Typical dynamics (rescaled)



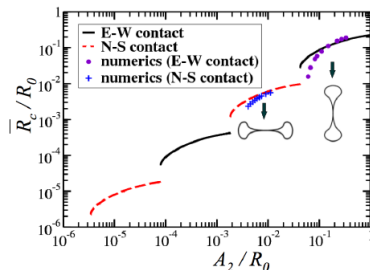
## Final shapes



We started from a small elliptical ( $m = 2$ ) perturbation on top of circular bubble. The shape of the bubble remained smooth throughout the dynamics and typically evolved in one or two contacts.

# Outcomes

- ▶ The outcome depends periodically on initial amplitude of the perturbation.
- ▶ Final shape has one or two contact points
- ▶ Strongly elongated shape observed for special initial conditions



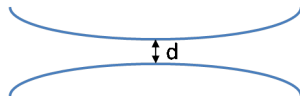
Three lobe shape



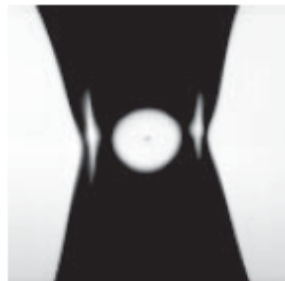
Aspect ratio  $L/d \approx 90$

# Contact event

- ▶ Perfectly regular dynamics with free surface approximation: layer width behaves like  $d \propto t_c - t$ , surface curvature  $K \rightarrow \text{const}$
- ▶ Air pressure grows like  $p \propto (t_c - t)^{-1}$  and excites capillary waves resulting in satellite bubble with  $R \approx 5 - 10 \mu\text{m}$
- ▶ Similar to processes happening during droplet splashing on solid surfaces (Mandre et.al., PRL 2009)

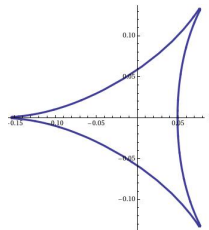
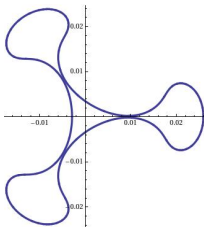
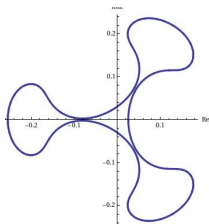


Satellite bubble



# Three fold symmetry

$m = 3$  perturbation



Smooth surface contact is the generic outcome for  $m = 3$  symmetry. However, singular cusp shapes are observed for special initial conditions.

# Conclusions

- ▶ Bubble formation is accompanied by a singular neck reconnection process
- ▶ Cross section evolution can be effectively described by a 2D free surface hydrodynamics model
- ▶ Dynamics is very sensitive to initial perturbations, but generic outcome is smooth contact

## Open questions

- ▶ Dynamics after the contact
- ▶ 3D effects
- ▶ Analytical structure of the solutions ?