

# The Method of Characteristics

Recall that for the first order linear wave equation

$$u_t + cu_x = 0, \quad u(x, 0) = f(x),$$

solutions are constant along lines of the form  $x - ct = x_0$ . To determine the value of  $u$  at  $(x, t)$ , we can traverse these lines until we get to  $t = 0$ , and then determine the value of  $u$  from the initial condition. The result is  $u(x, t) = u(x - ct, 0) = f(x - ct)$ .

There are many extensions to this simple idea. We begin by describing the situation for linear and almost linear equations.

## 1 Homogeneous transport equations

We first consider initial value problems of the form

$$u_t + c(x, t)u_x = 0, \quad u(x, 0) = f(x), \quad -\infty < x < \infty. \quad (1)$$

Let  $X(T)$  be any "trajectory" in the  $(x, t)$  plane, so that  $x = X(t)$  is a point on this trajectory. How does  $u$  evolve as we move along this trajectory? The chain rule implies

$$\frac{d}{dT}u(X(T), T) = X'(T)u_x(X(T), T) + u_t(X(T), T).$$

If we happen to pick  $X'(T) = c(X(T), T)$ , then

$$\frac{d}{dT}u(X(T), T) = c(X(T), T)u_x(X(T), T) + u_t(X(T), T) = 0$$

by virtue of equation (1). Thus  $u$  is constant along ALL curves which are solutions of the ordinary differential equation  $X'(T) = c(X, T)$ . To solve for  $u$  at some prescribed point  $(x, t)$ , we go "backward" along the curve  $X(T)$  until we hit time zero, and since  $u$  is constant along this curve, we find that the value of  $u$  is determined by the initial condition. In other words, if  $X(t) = x$ , then  $u(x, t) = u(X(0), 0) = f(X(0))$ .

The curves  $X(T)$  that solve the initial value problem

$$X'(T) = c(X, T), \quad X(t) = x, \quad (2)$$

are called *characteristics*. For the purpose of finding characteristics,  $(x, t)$  is a *fixed constant*, referring to the end point of the characteristic.

**Example 1.** Solve  $u_t + xu_x = 0$  with initial condition  $u(x, 0) = \cos(x)$ .

*Solution.* A characteristic curve passing through  $(x, t)$  will solve

$$X'(T) = X(T), \quad X(t) = x,$$

whose solution is  $X(T) = x \exp(T - t)$ . Since  $u$  is constant along the characteristic,

$$u(x, t) = u(X(0), 0) = u(xe^{-t}, 0) = \cos(xe^{-t}).$$

**Example 2.** We want to solve

$$yu_x = xu_y, \quad u(0, y) = 2y^2 \text{ for } y > 0 \quad (3)$$

*Solution.* This equation can be written in the form (1) as

$$u_x - \frac{x}{y}u_y = 0,$$

treating  $x$  like the time variable. Let  $Y(X)$  denote characteristic curves, which solve

$$Y'(X) = -\frac{X}{Y}.$$

Separating variables  $YdY = -XdX$  leads to  $X^2 + Y^2 = C$ ; in other words, characteristics are closed curves encircling the origin. If a characteristic curve passes through  $(x, y)$ , it is described implicitly by  $X^2 + Y^2 = x^2 + y^2$ . Setting  $X = 0$  means that on the  $y$ -axis,  $Y^2 = x^2 + y^2$ . Since the solution is constant along characteristics, using the side condition in (3) gives

$$u(x, y) = u(X, Y) = 2Y^2 = 2(x^2 + y^2).$$

Notice that if a boundary condition were imposed on the entire  $y$ -axis, then characteristic curves would intersect this boundary both at  $(0, y)$  and  $(0, -y)$ . Unless  $u(0, y) = u(0, -y)$  for every  $y$ , this problem would not have a solution.

## 1.1 Inhomogeneous transport equations

We can also solve equations of the form

$$u_t + c(x, t)u_x = g(u, x, t), \quad u(x, 0) = f(x), \quad -\infty < x < \infty. \quad (4)$$

The only difference between this and equation (1) is that  $u$  is not constant along characteristics, but evolves according to a first order ordinary differential equation

$$\frac{d}{dt}u(X(t), t) = g(u, X(t), t). \quad (5)$$

In other words, if we let  $U(T) = u(X(T), T)$  be the solution *restricted to a single characteristic*, it solves an initial value problem,

$$U'(T) = g(U, X(T), T), \quad U(0) = u(X(0), 0) = f(X(0)).$$

Thus, to find  $u$  at some point  $(x, t)$ , we go *backwards* along the characteristic that ends at  $x$  until time zero, then solve the ODE (5) *forwards* until  $T = t$ .

## 1.2 The method of characteristics for linear problems

We can summarize the ideas above as an algorithm:

1. **Find the characteristic terminating at  $(x, t)$ :** Solve  $X'(T) = c(X, T)$  with the “final” condition  $X(t) = x$ . Note that the solution for  $X(T)$  will depend on  $x$  and  $t$  as parameters.
2. **Determine the solution along a characteristic:** Solve  $U'(T) = g(U, X(T), T)$  subject to initial condition  $U(0) = U(X(0), 0)$ . Again the solution depends on  $x$  and  $t$  as parameters.
3. **Find the solution at the endpoint of the characteristic:** The solution of the PDE at  $(x, t)$  is simply  $u(x, t) = U(t)$ .

Here are a few examples of how this is used.

**Example 1.** Solve

$$u_t + (x + t)u_x = t, \quad u(x, 0) = f(x).$$

*Solution.* Characteristic curves solve the ODE

$$X'(T) = X + T, \quad X(t) = x.$$

This equation has a particular solution,  $X_p = -T - 1$ ; the general solution is therefore  $X(T) = Ce^T - T - 1$ . Using the condition  $X(t) = x$ , we find that

$$X(T) = e^{T-t}(x + t + 1) - T - 1.$$

Now we need to find how  $u$  changes along the characteristic, by solving

$$U'(T) = T, \quad U(0) = f(X(0)) = f(e^{-t}(x + t + 1) - 1).$$

whose solution by direct integration is

$$U(T) = f(e^{-t}(x + t + 1) - 1) + \frac{1}{2}T^2.$$

Finally, the solution at  $(x, t)$  is simply the value at the endpoint of the characteristic

$$u(x, t) = U(t) = f(e^{-t}(x + t + 1) - 1) + \frac{1}{2}t^2.$$

**Example 2.** Solve the nonlinear problem

$$u_t + 3u_x = -u^2, \quad u(x, 0) = f(x).$$

*Solution.* In this case, characteristics solve  $X'(T) = 3$  with  $X(t) = x$ , so that  $X = 3(T - t) + x$ . Along each characteristic, the solution evolves according to

$$U'(T) = -U^2(T), U(0) = f(X(0)) = f(-3t + x)$$

. Separating variables gives  $dU/U^2 = -dT$ , and integration produces  $1/U = T + C$ . Using the initial condition, one gets  $C = 1/f(x - 3t)$  and

$$U(T) = \frac{1}{T + 1/f(x - 3t)}.$$

The final solution is obtained by setting  $u(x, t) = U(t)$ .

**Example 3.** Suppose water flows over a landscape whose elevation is described by  $h(x)$ . A simple model for surface water flow says that the flow velocity is equal (in the right units) to  $-h'(x)$ . It follows that if  $u(x, t)$  is the depth of water, then the flux of  $u$  is  $J = -h'(x)u$ . In the absence of sources  $u$  satisfies the conservation equation  $u_t + (-h'(x)u)_x = 0$ , which can be written in the form (4) as

$$u_t - h'(x)u_x = h''(x)u. \tag{6}$$

The term on the right accounts for the fact that water will accumulate in valleys where  $h'' > 0$ , and is depleted from hills where  $h'' < 0$ .

Consider a simple model for a valley where  $h = x^2$ , and suppose that the initial depth is localized as

$$u(x, 0) = \begin{cases} 1 & |x| \leq 1 \\ 0 & |x| > 1 \end{cases}$$

Equation (6) then reads  $u_t - 2xu_x = 2u$ , and characteristics solve  $X'(T) = -2X$  together with the terminal condition  $X(t) = x$ . The solution of this problem is

$$X(T) = xe^{2(t-T)}.$$

The solution on characteristics now solves  $U' = 2U$  with initial condition

$$U(0) = \begin{cases} 1 & |X(0)| \leq 1 \\ 0 & |X(0)| > 1 \end{cases}$$

Therefore  $U(T) = e^{2T}$  if  $|X(0)| = |xe^{2t}| < 1$ , or zero otherwise. It follows that when  $t = T$ ,

$$u(x, t) = \begin{cases} e^{2t} & |x| \leq e^{-2t} \\ 0 & |x| > e^{-2t} \end{cases}$$

The depth of the fluid layer therefore increases exponentially, but its width decreases exponentially in a way such that  $\int u dx$  remains constant.