

Frontier Probability Days Tucson, Arizona

Approximate counting of connected components with random walks

Florian Sobieczky

Monday, 19th of May, 2014

This talk is dedicated to Evi Nemeth, lost at sea.

Scale Spaces

Segmentation

Number of Connected Components

Counting with Random Walks

Scale Spaces

- ▶ $G = \langle V = \mathbb{Z}^2, E = N.N. \rangle$, and
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- ▶ Idea: Splitting up information of image into different scales which label different 'derived images' according to different degree of detail (Burt 81, Crowley 81, Witkin 83)
- ▶ Typical Properties are: **Causality**, Linearity, Scale Invariance, Semi-group property, Isotropy, Homogeneity, ...

Comparison of two scale spaces



Figure: Comparison of $\Phi_t[f](x) := \mathbb{E}^x[f(B_\tau)]$ (top row; B_t is Brownian Motion) with GIMP's 'Selective Gaussian Blur', where $\tau = \inf\{t > 0 \mid \int_0^t |f(B_s)|^2 ds > \epsilon\}$. ϵ is a scale parameter of Φ_t corresponding to the tolerance of (pathwise!) greyvalue variance. Φ_t outperforms the Selective Blur, as seen in third column (optimal case) .

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- ▶ Example: Grady-Model: – Labelling technique (linear, solves Bottlenecks' problem)
L.Grady, E.L. Schwarz: 'Isoperimetric Graph partitioning for Data Clustering and Image Segmentation' PAMI, 2004

Description of the Hoshen-Kopelman Algorithm

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- ▶ For Image of Order N there are $O(N)$ steps
- ▶ Drawback: Doesn't treat 'almost separated clusters' as two.

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- ▶ Solves 'Bottleneck' Problem.

Counting the Number of Connected Components

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- ▶ Union-Find Algorithms (HK, etc.)
Problem: Does not detect 'vague boundaries between segments'

Feature detection on Satellite Images

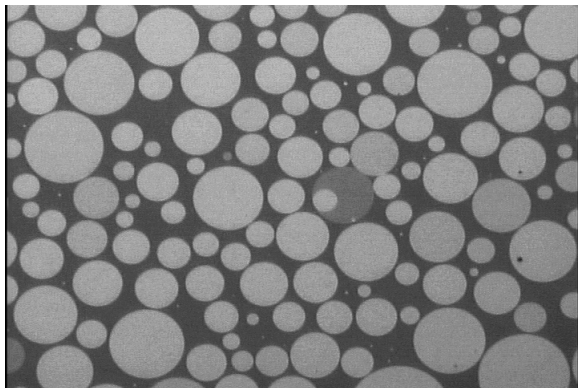


Figure: From courtesy of J.E.Maclennan: 'Liquid Crystallography' (Noisy Picture)

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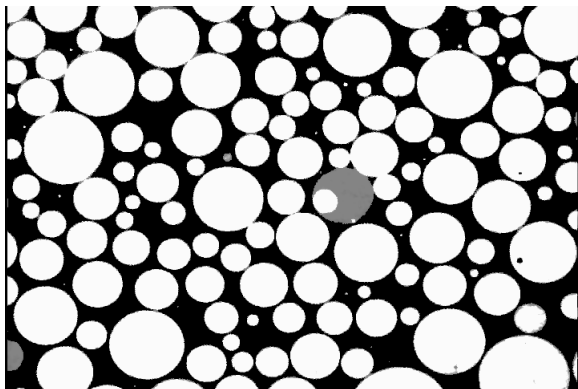


Figure: From courtesy of J.E.Maclennan: 'Liquid Crystallography' (Noise removal induces bottlenecks)

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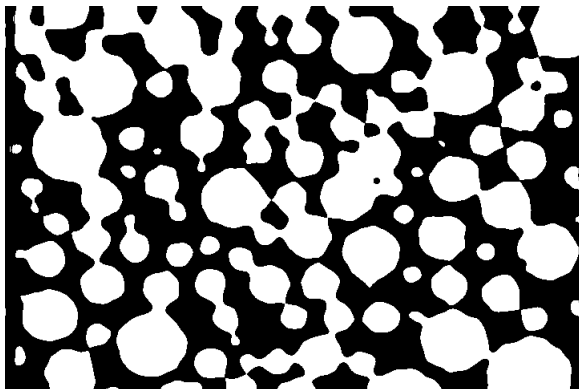


Figure: Strong Noise removal induces many new bottlenecks (Still want to find approximately same number of components)

Counting ‘nearly’ separate components with RW’s

- ▶ General Setting: $G = \langle V, E \rangle$ and $\{V_N\} : V_N \subset V_{N+1} \rightarrow V$
Let G be infinite, transitive, amenable.
 $\Omega = 2^E, \mu \in \mathcal{M}_{1,+}(\Omega), \text{Aut}(G)$ -invariant
 $\omega \in \Omega$ and $H_N(\omega) = \langle V, \omega^{-1}(\{1\}) \rangle | V_N$.

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- ▶ $\frac{1}{N} \text{Tr}[e^{-t\mathcal{L}_N}] = \mathbb{P}[X_t = X_0 \mid X_0 \sim \text{UNIF}(V)] =: \bar{P}_N(t)$
This is the return probability if the initial distribution is uniform on V_N .

Counting 'nearly' separate components with RW's

- Observe: For $G = \langle \mathbb{Z}^2, N.N. \rangle$, with $0 = \tilde{\lambda}_0 < \tilde{\lambda}_1 < \dots < \tilde{\lambda}_j$ the spectrum of j -th component:

Shape of j th component	Order of mag of $\tilde{\lambda}_1$ in $\tilde{N} := \tilde{N}_j$:
Circle	\tilde{N}^{-1}
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- ▶ Choose $N_1(N)$ to be the minimum cardinality of a dumbbell's vertex-set, which should still be counted as two components. Let $\hat{N}(N)$ be the maximal cardinality of any *connected* component. Then, choose $\epsilon_N, c > 0$ such that

$$\frac{c}{N_1 \log N_1} < \epsilon_N < \frac{1}{\hat{N}}.$$

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Counting ‘nearly’ separate components: Results

- **Prop. 1** If N suff. large, $M_N^{(\epsilon_N)}$, defined by

$$M_N^{(\epsilon)} = \dim(\text{span}\{v \in R^{V_N} \mid (1 - P_N)v = \lambda v \text{ and } \lambda < \epsilon\})$$

is the number of connected or nearly separated components if they can only be disks, dumbbells, or touching disks with the smaller of the two touching disks with cardinality N_1 fulfilling

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- ▶ **Prop. 3** $M_N^{(\epsilon_N)} \leq N \cdot \bar{P}_N(t)$, where $t = \hat{N} \ln(\hat{N}^2/N)$.

Ideas from the Proof:

- ▶ Assume $|V_N| = N$ (for simplicity). Let:

$$\mathbb{E}_N [f(\bar{N}, \{\bar{\lambda}\})] := \frac{1}{N} \sum_{v \in V_N} f(\bar{N}(v), \{\bar{\lambda}(v)\})$$

where $\bar{N}(v) = \tilde{N}_j$ such that the j -th component with size \tilde{N}_j .

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- ▶ then, with $\tilde{\mathbb{E}}_N [f(\tilde{N}, \{\tilde{\lambda}\})] := \sum_{j=1}^{M_N} \tilde{p}_j f(\tilde{N}_j, \{\tilde{\lambda}_j\})$:

$$\mathbb{E}_N [f(\bar{N}, \{\bar{\lambda}\})] = \tilde{\mathbb{E}}_N [f(\tilde{N}, \{\tilde{\lambda}\})]$$

the expected value with respect to the size biased distribution over the space of labels of the connected components is the same as the expected value with respect to the uniform distribution over vertices in V_N .

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- ▶ The function on the left is decreasing in t , the one on the right increasing. Replacing the LHS with an upper bound and the RHS with a lower bound will lead to an equation which will only be solved for a greater t , yielding an upper bound for t_1 .

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- ▶ The following bounds for the LHS and RHS are available:
Let $\epsilon = \epsilon_N := \frac{c}{\widehat{N} \ln \widehat{N}}$ for some $c > 0$, and $\widehat{N} := \max_j \widetilde{N}_j$)

Bound (\downarrow) - Side(\rightarrow)	LHS	RHS
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- ▶ Similarly, a lower bound for t_1 can be obtained by using the monotonicity of LHS and RHS in t in the reversed way:
 $\exists_{t < t_1} \frac{\widehat{N}}{N} e^{-t/\widehat{N}} = \frac{1}{\widehat{N}} \Rightarrow t_1 > \widehat{N} \ln(\widehat{N}^2/N)$

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Therefore, criterion for tightness:

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- ▶ Example: $\hat{N} \sim \sqrt{N} \ln N$
i.e. the largest component must be 'slightly larger' than \sqrt{N} .

Thank you for a great conference!



Figure: From Saguaro National Park. See more pictures here:
<http://web.cs.du.edu/~sobieczk/Tucson>