

Test 2 recap

remaining material 4.2-4.6, 5.1-5.3, 6.1-6.5

We may end up between 15+20 quizzes in here. ^{Test 3 somewhere}
 in which case I will count the best 15 + drop lowest others
 then rescale by $\frac{20}{15} = \frac{4}{3}$ to make pts. match!

Subspaces of \mathbb{R}^n type 0 set of solns. to homog. eqn.
 for some matrix A
 set of x s.t. $Ax=0$

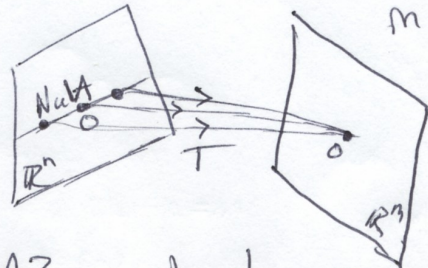
Def The null space of an $m \times n$ matrix A is the set of solns. to homog. eqn. $Ax=0$

$\{x \mid Ax=0\}$ or $\{x : Ax=0, x \in \mathbb{R}^n\}$
 so A must be $m \times n$

$Nul A = \{x : x \in \mathbb{R}^n, Ax=0\}$

so $Nul A \subseteq \mathbb{R}^n$, vectors in \mathbb{R}^n which map to 0 in \mathbb{R}^m by T .

Think of a lin. trans, T w/ standard matrix A
 then $T(x) = Ax$ and $Nul A =$ set that is mapped to 0 by T .



ex for $A = \begin{bmatrix} 2 & 1 \\ -2 & -1 \end{bmatrix}$ is $u = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ in $Nul A$?
 check if $Au = \vec{0}$ if yes then yes if no then no.

why do we call this the null space?

pf of thm 2
 $Nul A \subseteq \mathbb{R}^n$ b/c A has n cols.

- show ① $\vec{0} \in Nul A$
 ② $\forall x, y \in Nul A, x+y \in Nul A$
 ③ $\forall x \in Nul A, \forall c \in \mathbb{R}, cx \in Nul A$

$\therefore x \in Nul A \Rightarrow x \in \mathbb{R}^n$
 $\therefore Nul A \subseteq \mathbb{R}^n$

$Nul A = \{x : Ax=0, x \in \mathbb{R}^n\} \subseteq \mathbb{R}^n$

$A(\vec{0}) = \vec{0}$ so $\vec{0} \in Nul A$

$\hat{\mathbb{R}}^n \hat{\mathbb{R}}^m$ let $x, y \in Nul A$

$\therefore Ax = \vec{0}$ and $Ay = \vec{0}$

so consider $A(x+y) = Ax + Ay = \vec{0} + \vec{0} = \vec{0}$
 by linearity.

and let $c \in \mathbb{R}$

$A(cx) = cAx = c\vec{0} = \vec{0}$

thus $Nul A$ is a subspace of \mathbb{R}^n .

Thm 2 for $A \in \mathbb{R}^{m \times n}$

$Nul A$ is a subspace of \mathbb{R}^n
 set of all solns. to $Ax=0$ of m homog. eqns. in n unknowns is a subspace of \mathbb{R}^n .

EX 2 let $H = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \in \mathbb{R}^4 : \begin{matrix} a-b+3c=4d \\ \text{and} \\ d-b=c \end{matrix} \right\}$

Show H is a subspace of \mathbb{R}^4 .
 rearrange eqns.

$a-b+3c-4d=0$
 $-b-c+d=0$
 $\therefore A = \begin{bmatrix} 1 & -1 & 3 & -4 \\ 0 & -1 & -1 & 1 \end{bmatrix}$
 and $x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$

the solns. to $Ax=0$

is H . $\therefore H = Nul A$ and by thm 2 H is a subspace of \mathbb{R}^4
 (b/c A is 2×4)

You must have homog eqns. or a homog system, o.w. $\vec{0}$ is not a soln.
 If not homog, soln. set could be empty, if sys. was inconsistent!

Explicit description of Nul A

Solving $Ax=0$ gives an explicit description of Nul A

$Nul A = \{x : Ax=0, x \in \mathbb{R}^n\}$ is an implicit defn.
 you must check a condition to know if $x \in Nul A$

(\nexists) a formula for what objects in Nul A look like.
 that would be explicit for ex. how it was defined in last example!

EX 3 from sec. 1.5
 let $A = \begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & -8 \end{bmatrix}$ find a spanning set for the nullspace of A.

1st solve $Ax=0$ for general soln. w/ free variables (if any?)
 row reduce aug. mat. $[A \ 0]$ to REF.

$$A \sim \begin{bmatrix} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & -4 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -4/3 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 - \frac{4}{3}x_3 = 0$$

$$x_2 = 0$$

$$0 = 0$$

x_3 is free

so $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4/3 x_3 \\ 0 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 4/3 \\ 0 \\ 1 \end{bmatrix}$ (p.v.f.)

we decompose general soln. into lin. comb. of vectors w/ wts. = free variables.

EX 3.5 suppose $B = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & 4 & 5 & 8 & -4 \end{bmatrix}$ and $[B \ 0] \sim \begin{bmatrix} 1 & -2 & 0 & -1 & 3 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

thus $x_1 - 2x_2 - x_4 + 3x_5 = 0$

basic $\rightarrow x_3 + 2x_4 - 2x_5 = 0$ free

recall: \uparrow wts are basic all others are free

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 + x_4 - x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -1 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

$\vec{u} \quad \vec{v} \quad \vec{w}$

so $\vec{x} = x_2 \vec{u} + x_4 \vec{v} + x_5 \vec{w}$

all lin. combs. of $\vec{u}, \vec{v}, \vec{w}$ form Nul A

so $Nul A = \text{Span}\{\vec{u}, \vec{v}, \vec{w}\}$

Facts: since these vectors are nonzero and correspond to spanning vectors w/ wts. equal to free variables, the only way a lin. comb. of these is $\vec{0}$ is if all free variables are 0.
 ② If Nul A has more variables than just $\vec{0}$, then # of spanning vectors = # free variables in $Ax=0$.

Column Space of a Matrix

defined explicitly w/ lin. combs.

Defn The column space of an $m \times n$ matrix A is the set of all lin. combs. of the cols. of A.

let $A = [a_1 \dots a_n]$, then $Col A = \text{Span}\{a_1, \dots, a_n\}$

Note: $Col A = \{b : b = Ax, x \in \mathbb{R}^n\} \subseteq \mathbb{R}^m$

Ax denotes a lin comb. of cols of A w/ wts. x

This note also says that $Col A = \{Ax : x \in \mathbb{R}^n\} = \text{Range}(T)$
 where $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $x \mapsto Ax$

Thm 3 If A is $m \times n$ then $Col A$ is a subspace of \mathbb{R}^m . (Note the subtle diff. w/ Thm 2.)

EX4 let $W = \left\{ \begin{bmatrix} 2a-b \\ -b \\ b-a \end{bmatrix} : a, b \in \mathbb{R} \right\} = \left\{ a \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix} + b \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} : a, b \in \mathbb{R} \right\}$
 find A s.t. $\text{Col } A = W$ rewrite W as lin. combs. $= \text{Span} \left\{ \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}$

thus let $A = \begin{bmatrix} 2 & -1 \\ 0 & -1 \\ -1 & 1 \end{bmatrix}$ so $W = \text{Col } A$.

recall (thm 4.1.4) m
 cols of A span \mathbb{R}^m
 $\iff Ax=b$ has a soln. $\forall b \in \mathbb{R}^m$

\rightarrow fact: for A $m \times n$, $\text{Col } A = \mathbb{R}^m \iff Ax=b$ has a soln. $\forall b \in \mathbb{R}^m$
~~conv:~~ $\iff A$ invertible (by FMT)

Contrast between Nul A and Col A

relationship between Nul A and Col A ? really they are dissimilar ex 5.7
 relationship given in sec. 4.6 w/ more theory!

EX5

- let A be 3×4
 ① $\text{Col } A \subseteq \mathbb{R}^k$, find k .
 ② $\text{Nul } A \subseteq \mathbb{R}^l$, find l .

Soln. ① cols of $A \in \mathbb{R}^3$
 so $\text{Col } A \subseteq \mathbb{R}^3$
 ② $x \in \mathbb{R}^4$ so that Ax is defined
 $\therefore \text{Nul } A \subseteq \mathbb{R}^4$.

Ask for non-square matrices
 A $m \times n$ w/ $m \neq n$
 $\text{Nul } A$ and $\text{Col } A$ are m different universes!
 Nul m comb. of vectors in \mathbb{R}^m can ever be a vector in \mathbb{R}^n unless $m=n$
 (think $m=2, n=3$)

what is $\text{Nul } A \cap \text{Col } A = \begin{cases} \emptyset & \text{when } n \neq m \\ \vec{0} & \text{usually when } n=m \end{cases}$
some sets containing $\vec{0}$ + other vectors m rare special cases.

See exs 6+7 in book

EX 7.5 let $A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$

find $\text{Nul } A$ and $\text{Col } A$.

what is $\text{Nul } A \cap \text{Col } A$?

As a subspace of \mathbb{R}^2 what is this isomorphic to?

See table on pg. 232

$\text{Nul } A = \{x : Ax=0, x \in \mathbb{R}^2\} = \{x : \begin{bmatrix} x_1 - x_2 \\ x_1 - x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}\}$
 $\text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} x \\ x \end{bmatrix} \right\} \subseteq \mathbb{R}^2$
 so $\text{Nul } A = \text{Col } A =$ set of vectors in \mathbb{R}^2 w/ 1st & 2nd entries the same.
 Graphically it's the line $y=x$ in \mathbb{R}^2 !
 \therefore this space is isomorphic to \mathbb{R} .

kernel + Range of Lin. Trans.

generalization of lin. trans. defn. from 1.8

A linear transformation T from a vect. sp. V to a vect. sp. W is a map that assigns a unique vector $T(x) \in W$ to each vector $x \in V$ s.t.

- (i) $T(u+v) = T(u) + T(v)$ $\forall u, v \in V, \forall c \in \mathbb{R}$
 (ii) $T(cu) = cT(u)$

The kernel (also called null space) of T is set of $u \in V$ s.t. $T(u) = \vec{0} \in W$.

The range of T is set of $y \in W$ s.t. $\exists x \in V$ s.t. $y = T(x)$

So kernel or $\ker(T) = \{u \in V : T(u) = \vec{0}\}$
 and range or $\text{Range}(T) = \{T(x) \in W : x \in V\}$

\therefore if \exists a matrix A s.t. $T(x) = Ax$
 then $\ker(T) = \text{Nul } A$ and $\text{Range}(T) = \text{Col } A$

Recall I mentioned that the derivative was a linear operator.

$$\frac{d}{dx}(af(x)+g(x)) = a f'(x) + g'(x)$$

EX8 let $V =$ vect. sp. of all real-valued fns. f defined on $[a, b]$ that are differentiable and have cts. derivatives f' on $[a, b]$

let $W =$ vect. sp. of all cts. fns. on $[a, b]$ and

$D: V \rightarrow W$ $f \mapsto f'$ so $D(f+g) = D(f) + D(g)$ and $D(cf) = cD(f)$ by props. of the derivative. So D is linear.

What is

$\ker(D)$ and $\text{Range}(D)$? $\ker(D) =$ constant fns. on $[a, b] \cong \mathbb{R}$, $\text{Range}(D) = W$.

EX9 consider $y'' + \omega^2 y = 0$ w/ $\omega =$ constant (models springs, vibrations, pendulum, voltage)

So \exists a linear transformation which maps $y = f(t)$ to $f''(t) + \omega^2 f(t)$. The kernel of this lin. trans. is the solutions to the DIFF EQ. So soln. see ex. 19 msec. 4.1.

practice problems

show subspace of \mathbb{R}^3 using 2 diff thms.

1. let $W = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} : a + 2b - 3c = 0 \right\} = \left\{ x = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3 : Ax = 0 \right\}$

So $W = \text{Null } A$ where $A = \begin{bmatrix} 1 & 2 & -3 \end{bmatrix}$

$W = \left\{ b \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix} : b, c \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix} \right\} = W = \left\{ \begin{bmatrix} -2b+3c \\ b \\ c \end{bmatrix} : b, c \in \mathbb{R} \right\}$

\therefore if $B = \begin{bmatrix} -2 & 3 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$ then $W = \text{Col } B$.

W is a subspace of \mathbb{R}^3 by thm 2 since $W = \text{Null } A_{1 \times 3}$ or by thm 3 since $W = \text{Col } B_{3 \times 2}$

2. let $A = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}_{3 \times 3}$

$v = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$ $w = \begin{bmatrix} 7 \\ 6 \\ -3 \end{bmatrix}$ Suppose you know $Ax = v$ and $Ax = w$ are both consistent. What can you say about eqn. $Ax = v+w$?

$Ax = v, Ax = w$ consistent $\Rightarrow \exists x, z \in \mathbb{R}^3$ s.t. $Ax = v$ and $Az = w$

So let $x = y + z$ then $Ax = A(y+z) = Ay + Az = v + w$

$\Rightarrow \exists$ a soln. to sys. $Ax = v+w$ $\therefore Ax = v+w$ is also consistent!

(could also state this in terms of $\text{Col } A$)